PCT/IB02/05295

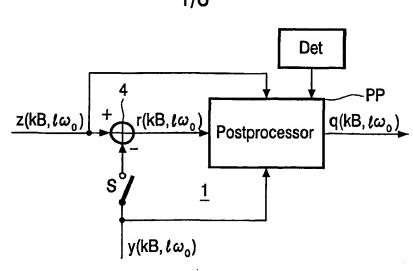
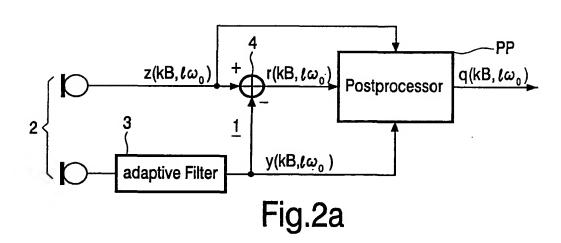


Fig.1



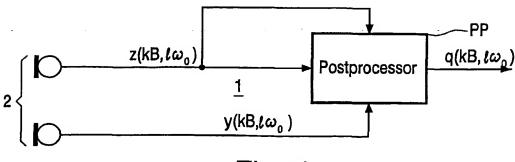
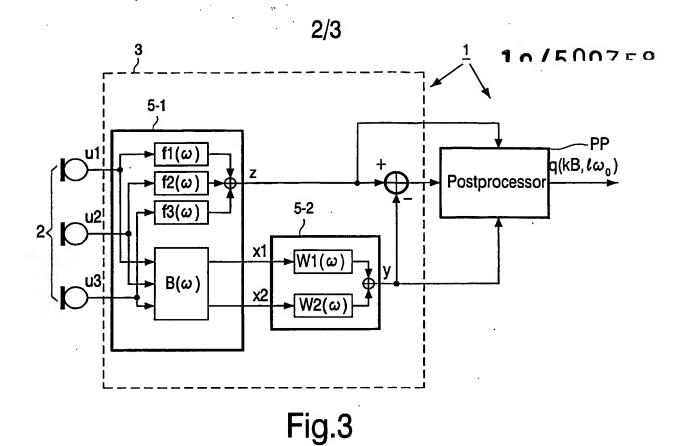


Fig.2b



 $z(kB, \ell\omega_0)$  +  $r(kB, \ell\omega_0)$  Postprocessor  $q(kB, \ell\omega_0)$   $y(kB, \ell\omega_0)$  adaptive Filter  $q(kB, \ell\omega_0)$ 

Fig.4

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